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Preface Chapter 1 Chapter 2 Chapter 3

Aug 16, 2020 · 5 Page 145, Lemma 42: See Lemma 41 of HK Khalil, Nonlinear Control, 2015, for better definitions of domains 6 Page 145, Lemma 43: Replace the last two sentences "If $D = \mathbb{R}^n$ and $V(x)$ is radially unbounded, then there exist class K_1 functions α_1 and α_2 such that the foregoing inequalities hold for all $x \in \mathbb{R}^n$ " by "If $D = \mathbb{R}^n$ and $V(x)$ is radially unbounded, then there exist class K_1 functions α_1 and α_2 such that the foregoing inequalities hold for all $x \in \mathbb{R}^n$ "

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Nonlinear Control Lecture#1 Introduction

solution over $[t_0, t_0 + \delta]$ Without the local Lipschitz condition, we cannot ensure uniqueness of the solution For example, $\dot{x} = x^{1/3}$ has $x(t) = (2t/3)^{3/2}$ and $x(t) \equiv 0$ as two different solutions when the initial state is $x(0) = 0$ The lemma is a local result because it guarantees existence and uniqueness of the solution over an interval $[t_0, t_0 + \delta]$, but

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